

BSART (Broadcasting with Selected Acknowledgements and Repeat Transmissions) for Reliable and Low-costed Broadcasting in the Mobile Ad-hoc Network

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Abstract. In this paper, we suggest enhanced broadcasting method, named 'BSART(Broadcasting with Selected Acknowledgement and Repeat Transmissions)' which reduces broadcast storm and ACK implosion on the mobile ad-hoc network with switched beam antenna elements that can enable bidirectional communication. To reduce broadcast storm, we use DPDP(Directional Partial Dominant Pruning) method, too. To control ACK implosion problem rising on reliable transmission based on ACK, in case of the number of nodes that required message reception is more than throughput, each node retransmit messages constant times without ACK which considering message transmission success probability through related antenna elements(R-method). Otherwise, the number of message reception nodes is less than throughput, each node verify message reception with ACK with these antenna elements(A- method). In this paper, we suggest mixed R-/A- method. This method not only can control the number of message transmitting nodes, can manage the number of ACK for each antenna elements. By simulations, we proved that our method provides higher transmission rate than legacy system, reduces broadcast messages and ACKs.

Keywords: selected broadcasting, mobile ad-hoc network, node selection

1 Introduction

Because every node roles not only host but router, the broadcasting method is indispensable to wireless ad-hoc network for searching special node's positioning information or indentifying existence of any node. To control broadcast storm problem which too heavily duplicated messages are occurred when nodes operate broadcasting, it is useful a method that only a few node receives forwarded

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message[1][2][3]. The CDS (connected dominant set) can be equal to forward node set for those network set, but it is proved that finding the lowest cost CDS is NP-complete problem. There are various heuristic methods to search CDS, the one method is source-dependent broadcasting which consists of only one CDS per whole network, another method is source-independent broadcasting which consists of one CDS per each network, the other method which mixes source-independent method and source-dependent method[2][3][5][6]. In general, the former method can reduce the number of selected nodes, the latter method can support node's mobility and it also can split up whole traffics.

The wireless ad-hoc network environment may increase the rate of error during transmission rather than wired network environment, and the probability of message loss is high because the signals interfere and collide with each other. The one solution of these problems is ACK transmission and the other solution is selective flooding which can receive partially overlapped messages [4][7][8]. But if all nodes that received broadcasting message response with ACK message, it may cause ACK implosion which many ACK messages occur simultaneously and it leads congestion[9]. Furthermore it can reduce the performance of link in the case of ACK message is missed, because nodes must retransmit messages[1][9].

Related researches show that the node which required receiving and forwarding is applied ACK response method, and dead-end node that required only receiving can receive duplicated message from neighboring nodes in the wireless ad-hoc network environment with omnidirectional antennas[2][11]. But these methods select forwarding nodes that neighboring all dead-end nodes with definite number of forwarding nodes compulsory, it may increase the number of forwarding node. This means that the number of broadcasting messages and ACK messages are increased, and so it can't be appropriate solution for broadcast storm or ACK implosion.

The methods that reducing duplicated messages in the wireless ad-hoc network with directional antenna are message forwarding in the MAC layer, directional self pruning, three-hop horizon pruning and etc. But these research didn't consider reliable transmission or ACK implosion problem though they attempt to reduce broadcasting messages[5][8][12]. Most research considered just one of them, but Lou-Wu considered both problems[1][2][3][6][10][11][14][15].

In this paper, we suggest a low-cost, reliable broadcasting method with switched beam antenna which enables directional transmission on mobile ad-hoc network. Our method manages broadcasting storm with DPDP and in case of ACK implosion, we applies SART selectively. By simulation, we proved our method quite reduced both of broadcast storm and ACK implosion and enables reliable transmission with directional antenna on mobile ad-hoc network.

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2. System Model

The Mobile ad-hoc network that discussed in this paper is divided by not overlapped K sectors and we supposed that each sector contains switched beam antennas which controls each sector.

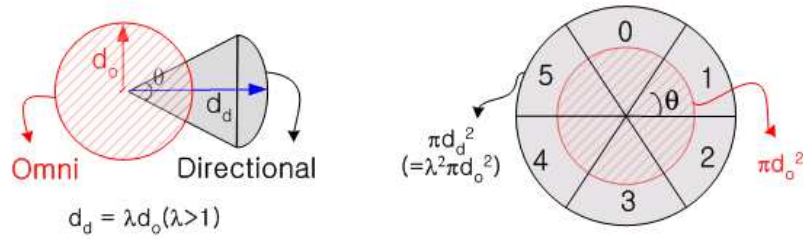


Fig. 1. omnidirectional antenna and directional antenna, directional antenna which consist of 6 antenna elements($K=6$)

Let G_o where the transmission gain using omni-directional antenna, G_d where the transmission gain using directional antenna, in general the following inequality comes, $G_d > G_o$. In case that omni-directional antenna using 10dBm power reaches 250m, but using the same antenna which beam angle setted by 60° , it reaches 450m[16]. A switched beam antenna that using only one antenna element at a time, omni-directional broadcasting can be realized by sequential sweeping process[16]. In other words, a clockwise antenna element 0, 1, 2, ..., $K-1$ transmits messages with constant delay. If it transmits only special antenna elements group, it can realize selective flooding, too. Let $d_d = \lambda d_o$ (where $\lambda > 1$, d_d : reaching distance using directional antenna, d_o : reaching distance using omni-directional antenna), the reaching area using directional antenna is larger than area using omni-directional antenna for λ^2 times, so we can regard network model that increasing λ^2 times node per neighbor node.

The mobile ad-hoc network can be described by unit disk graph $G=(V,E)$ where V is set of wireless mobile nodes and E is set of node's edge. A edge $(u,v) \in E$ means wireless link between node u and node v which can reach each other. We suppose that all wireless links (u,v) satisfy symmetrical property. In other words, if u can transmit messages to v , v can transmit to u , too. We supposed u 's neighbor nodes to u can reach and declare u 's neighbor nodes set to $N(u)$. By definition, $u \in N(u)$.

If we declare u 's 2-hop neighbor nodes set to $N(N(u))$ or $N_2(u)$, a inequality $\{u\} \subseteq N(u) \subseteq N_2(u)$ is established and $N(v) \subseteq N_2(u)$ follows if $v \in N(u)$. If we declare $N_h(u)$ that within h -hop nodes from u and $H_h(u)$ that h -hop nodes from u , a following

equation comes, $N_h(u) = N_{h-1}(u) \cup H_h(u)$ where $h \geq 1$ and $N_0(u) = H_0(u) = \{u\}$. For the convenience, we omit subscript if $h=1$.

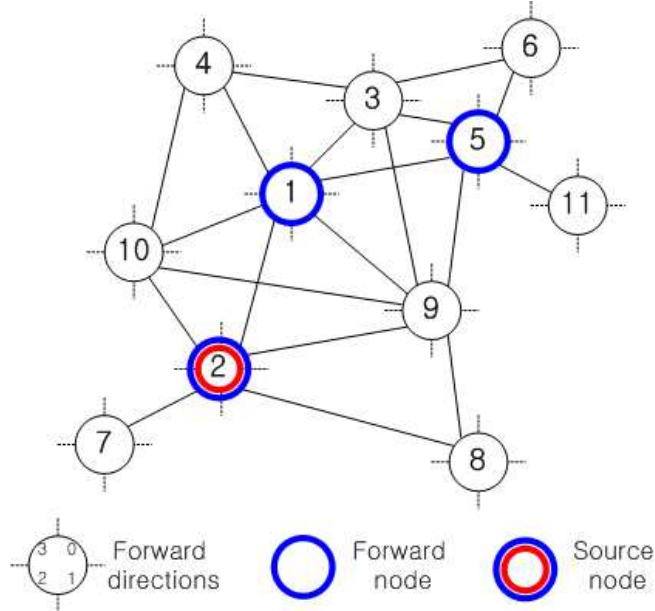


Fig. 2. an example using 4 antenna elements

Fig. 2 describes $N_2(1) = N(1) \cup H_2(1) = \{1,2,3,4,5,9,10\} \cup \{6,7,8,11\} = \{1,2,3,4,5,6,7,8,9,10\}$.

Nodes can communicate directly with antenna element i , where the nodes which using unoverlaped K antenna elements, so to speak 1-hop away nodes set declared to $N_{i \rightarrow}(u)$. Then $N_{i \rightarrow}(u) \subseteq N(u)$ and $N(u) = N_{0 \rightarrow}(u) \cup N_{2 \rightarrow}(u) \cup \dots \cup N_{K-1 \rightarrow}(u) \cup \{u\}$.

A degree of node u is $|N(u)| - 1 = |N_{0 \rightarrow}(u)| + |N_{2 \rightarrow}(u)| + \dots + |N_{K-1 \rightarrow}(u)|$ where $|N_{i \rightarrow}(u)|$ is the number of nodes that belongs to $N_{i \rightarrow}(u)$. We suppose that antenna element's direction for every node maintains fixed direction by using magnetic compass or etc..

Because radiowave travels straight, there are diagonal relationship established between antenna elements for u and v (where $u \in N(v)$) communicate each other. In other words, the antenna j where $0 \leq j \leq K-1$ which transmit messages u to v , the antenna that v uses must $(j + (K/2)) \bmod K$.

In fig. 2, the antenna is 1 when node 2 transmit messages to node 8, so node 8 can receive message from node 2 via antenna 3. If $D_{v \rightarrow u} = \{i | u \in N_{i \rightarrow}(v)\}$, $D_{v \rightarrow v} = \bigcup_{w \in V} D_{v \rightarrow w}$ where V is nodes set that satisfy $V \subseteq N(v)$. For example, $D_{8 \rightarrow 2} = \{3\}$, $N(10) = \{1,2,4,9\}$, $D_{10 \rightarrow N(10)} = D_{10 \rightarrow 1} \cup D_{10 \rightarrow 2} \cup D_{10 \rightarrow 4} \cup D_{10 \rightarrow 9} = \{0\} \cup \{1\} \cup \{0\} \cup \{1\} = \{0,1\}$ in fig. 2.

In this paper, we suppose that node u broadcast HELLO periodically for obtain neighbor node's state information. In other words, node v that receives HELLO from u , transmits HELLO to u via piggybacking to communicate with 1-hop neighbor node $N(v)$.

3. BSART: Broadcasting with Selected Acknowledgement and Repeat Transmissions

Suppose that node v gets self forwarding node set $F(v)$ and dead-end set $D(v)$ using DPDP. Then v gets nodes set T_i to transmit message that not classified $F(v)$ and $D(v)$ per antenna element $0, 1, \dots, K-1$, where $T_i = N_{i \rightarrow}(v) \cap \{F(v) \cup D(v)\}$, i means antenna element's ID, and $0 \leq i \leq K-1$.

Then v gets nodes set T_i to transmit message that not classified $F(v)$ and $D(v)$ per antenna element $0, 1, \dots, K-1$, where $T_i = N_{i \rightarrow}(v) \cap \{F(v) \cup D(v)\}$, i means antenna element's ID, and $0 \leq i \leq K-1$. In case that $|T_i|$ exceeds a constant number then nodes transmit messages repeatedly constant times (for convenience, we call this A-method), otherwise nodes identify message reception via ACK (for convenience, we call this R-method). For example, to prohibit receiving 3 messages per antenna simultaneously, set $c=3$.

It can increase congestion by ACK and messages generated simultaneously, if ACK identification (A-method) just as Low-Wu and method that get opportunity from neighbor nodes minimum 2 times are applied at the same time for the area that mixed $F(v)$ and $D(v)$, via each antenna element i because a network with directional antenna, each antenna can control separately [10]. And if one node receives ACK heavily, the ACK implosion occurs and this situation cause not only performance decrease, extreme delay.

Let the $M(v, s, \text{seq\#}, F(v), \text{mode}, \text{DATA})$ is message to broadcast where v is ID of forwarding node, s is broadcast message source node's ID, seq\# means sequential number of broadcast message that generated by s . s and seq\# are used for identifying overlapped or not. Data means transmission message. $F(v)$ is forward node set that acquired by DPDP. Besides, all v must get R_v which antenna elements set that to apply A-method and A_v which antenna elements set that to apply R-method. Then for every antenna element i where $i \in \{0, 1, \dots, K-1\}$, v calculates $T_i = N_{i \rightarrow}(v) \cap \{F(v) \cup D(v)\}$. If $|T_i| < c$, generate A_v to apply A-method. If $|T_i| \geq c$, v generates R_v to apply R-method. And then transmits M with each antennas. Specially, transmission via R_v antenna element, it retransmits $1/p$ times periodically where p is transmission success probability via antenna element i . Finally, mode in the message M sets to A when A-method is applied or sets to R when R-method is applied.

- $D(v)$: dead-end node set for v
- $F(v)$: forward node set for v
- $N_{i \rightarrow}(v)$: neighbor node set which v can transmit message with antenna element i
- TX_{\max} : throughput of retransmission
- WAIT_{\max} : waiting time to receive ACK
- T_{int} : time slot for transmission M
- tx_cnt_i : the number of transmission times via antenna element i
- $\text{timer}_{\text{wait}}^i$: timer that waiting ACK after transmits M via antenna element i
- A_v : antenna element set for v to apply A-method
- R_v : antenna element set for v to apply R-method
- P_v^i : nodes set that response with ACK when receives M via antenna element i where $i \in A_v$ where $P_v^i = N_{i \rightarrow}(v) \cap \{F(v) \cup D(v)\}$. If, $i \in R_v$, $P_v^i = \phi$.

- ack_req_u : in case of waiting ACK from neighbor node u where $|P_v^i| < c$ and $u \in P_v^i$ set to 1, otherwise set to 0 where $P_v^i = N_{i \rightarrow}(v) \cap \{F(v) \cup D(v)\}$.
- $acked_u$: set 1 when receives ACK from $ack_req_u=1$, otherwise 0
- $ACK(w, v, s, sqn\#)$: ACK for $M(v, s, seq\#, F(v), mode, DATA)$

Algorithm: BSART(Broadcasting with Selected Acknowledgements and Repeat Transmissions)

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input:  $M(u, s, seq\#, F(u), P_u, mode, DATA), c$ 
output:  $A_v, R_v, F(v), M(v, s, seq\#, F(v), mode, DATA)$ 
initial state:  $tx\_cnt_i=0; A_v=R_v=\phi$ ; for all  $i \in \{0, 1, \dots, K-1\}$ ,  $P_v^i = \phi$ 

// supposed that ACK can not be lossed
case 1: nove  $v$  is a broadcast source
  1.1  $v=s; seq\#=seq\#+1$ 
  1.2  $B(u, v) = N(v); U(u, v) = H_2(v) // u = \phi$ 
  1.3 jump to 2.4

case 2: in case that receive  $M(u, s, seq\#, F(u), mode, DATA)$  from neighbor node  $u$ 
  2.1 if  $mode=A, v \in F(u)$ , execute followings, otherwise jump to 2.2 // ACK transmission
    2.1.1 if  $M$  is overlapped, stop.
    2.1.2 transmit  $ACK(v, u, s, seq\#)$  via antenna element  $f$  which received  $M$ , jump to 2.3
  2.2 if  $M$  is not overlapped, receive  $M$  and stop // dead-end node
  2.3  $B(u, v) = N(v) - N(u); U(u, v) = H_2(v) - N(u) - N(N(v) \cap N(u))$ 
  2.4 calculate  $F(v)$  with DPDP
  2.5 for each antenna element  $i (i=0$  to  $K-1)$ , calculate  $P_v^i = N_{i \rightarrow}(v) \cap \{F(v) \cup D(v)\}$  then execute followings
    2.5.1  $i$  where  $|P_v^i| \geq c$  execute followings, or jump to 2.5.2 // R-method
      2.5.1.1  $R_v = R_v \cup \{i\}$ .
      2.5.1.2 for all  $x$  where  $x \in P_v^i$ ,  $ack\_req_x=0$ 
      2.5.1.3  $mode=R; P_v=\phi$ . // retransmission mode
    2.5.2 if  $|P_v^i| < c$  // A-method
      2.5.2.1  $A_v = A_v \cup \{i\}$ .
      2.5.2.2  $mode = A$ . // ACK waiting mode
      2.5.2.3 for all  $w$  where  $w \in P_v^i$ ,  $ack\_req_w=1$ . //

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set ACK request

2.6 each antenna element i execute followings by sequential sweeping

2.6.1 if $i \in R_v$, transmit $M(v, s, \text{seq}\#, F(v), \text{mode}, \text{DATA})$ via antenna element i $1/p$ times retransmit every T_{int} time slot

2.6.2 if $i \in A_v$, execute followings via antenna element i

2.6.2.1 $\text{timer}_i:\text{wait} = \text{WAIT}_{\text{max}}$

2.6.2.2 transmit $M(v, s, \text{seq}\#, F(v), \text{mode}, \text{DATA})$

case 3: in case that receive $\text{ACK}(w, v, s, \text{seq}\#)$ from neighbor node w via antenna element f

3.1 if $f \in A_v$ and $\text{ack_req}_w=1$, execute followings

3.1.1 $\text{acked}_w=1; \text{ack_req}_w=0;$

3.1.2 $P_{v=}^f = P_{v=}^f - w$. if $P_{v=}^f = \phi$, $\text{timer}_f \text{ wait} = \phi$

case 4: when timer $\text{timer}_i^{\text{wait}}$ has expired and $\text{tx_cnt}_i < \text{TX}_{\text{max}}$, $P_{v=}^f \neq \phi$

4.1 $\text{timer}_i^{\text{wait}} = \text{WAIT}_{\text{max}}; \text{tx_cnt}_i = \text{tx_cnt}_i + 1.$

4.2 set $F(v) = P_{v=}^f$ transmit M via antenna element i

In case that broadcast source node is 0, we will apply BSART. In this case, we suppose that $c=2$, so when only one forward node per antenna element, nodes response with ACK and suppose that if node v transmit M with only one directional antenna element, put the transmission success probability p set to $1/2$. By algorithm 2.3 and 2.4, we will get $B(\phi, 0) = N(0) - N(\phi) = N(0) = \{0, 1, 2, 3, 4, 6, 8\}$, $U(\phi, 0) = H_2(0) - N(\phi) - N(N(\phi) \cap N(0)) = H_2(0) = \{5, 7, 9\}$, $F(0) = \{2, 4, 8\}$ ($F(0) = \{3, 6, 8\}$, too). By algorithm 2.5 and 2.6 we will get $R_0 = \{0, 1\}$, $A_0 = \{2, 3\}$, $P_{20} = \{4\}$, $P_{30} = \{6\}$. Because the transmission success probability $p=1/2$, M will be transmitted 2 times with antenna 0, 1. By 2.5.2, node 2, 3 included A_0 will wait ACK. That is to say $\text{ack_req}_4=1$, $\text{ack_req}_6=1$. Same way node 0, 4, 8 which included $F(0) = \{2, 4, 8\}$, $F(2) = \phi$, $A_2 = \{0\}$, $R_2 = \phi$, $P_{20} = \{7\}$, $F(4) = \phi$, $A_4 = \{3\}$, $R_4 = \phi$, $P_{34} = \{5\}$, $F(8) = \phi$, $A_8 = \{1\}$, $R_8 = \phi$, $P_{18} = \{9\}$.

If supposed that ACK can not be lossed, consider messages that generated by BSART algorithm in case $c=2$. A message transmission that required ACK occurs 5 times with A-method, so ACK occurs 5 times. In case that applied R-method, messages are transmitted by antenna element 0, 1, broadcasting is accomplished 2 times per each antenna element regardless the number of receiver nodes. In other words, number of message which twice retransmission, so total number of occurred message is $14 (= 5 + 5 + 2 \times 2)$. Because receive nodes can receive with 4 antennas, node 0 generates 4 messages. In the same way, node 2 generates 2 messages, node 3, 4, 5, 8 generates 1 message each other. If transmission successes without ACK implosion, ACK occurs from forward node set $\{1, 2, 3, 4, 5, 8, 9\}$ for each except source node 0. Therefore 7 messages are generated and this is more than BSART. Moreover it is the minimum number that can be generated besides at the node 0 can occur ACK implosion if it receives 2 ACK with antenna 0, 1.

4. Experiments and Evaluation

We considered 1000×1000 array with 20, 40, 60, 80, 100 nodes and nodes distributed by random number generator. Table 1 shows major parameters. Compared protocols are BF(blind flooding), HHH, SHJ, and etc. [8] [16]. The BF generates many overlapped messages but the message transmission ratio is high.

The speed of node is set to 0-20m/s and we supposed random-way point. Considered HHH, each forward node set one forwarding node per each direction. A designated node transmits message to all direction except received direction when message received. In the SHJ algorithm, each node u forwards

broadcast message with neighbor node information $N(u)$, and v which receives that message f direction which satisfies $N_f(v)-N(u)-\{u\} \neq \phi$. The simulation items as follows.

- forwarding direction (antenna element) ratio
- message forwarding ratio by number of nodes and antenna elements and movement speed
- ACK message processing time as number of antenna elements

Table 1. major parameters for simulation

<i>Parameter</i>	<i>Value</i>
TXmax	4
K	4, 6, 8
WAITmax	10
c	2, 3, 4, 5
p	0.3

The experiments carried with NS-2 simulator and we programmed each module with C++ and Tcl/Tk.

Fig. 3 shows selected antenna elements ratio which in order to broadcast in case that put the number of nodes to 20, 40, 60, 80, 100. In the case of BSART, less than 30% antenna elements are used, that is, $1.2(=4 \times 0.3)$ per nodes and it is very similar to HHH algorithm. In the case of BF algorithm, as number of nodes increase, messages are transmitted to all direction. SHJ case, it uses 2.4 the maximum.

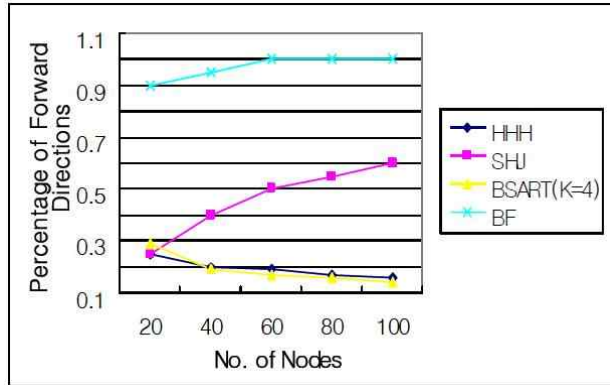


Fig. 3. antenna element ratio per node

Fig. 4, 5, 6 shows message transmission ratio as number of nodes, antenna element and movement speed respectively. As number of nodes increases, the transmission ratio increases and HHH shows the lowest transmission ratio. Except BF, the transmission ratio is similar to each other and BSART and DCB show almost 100% in case that number of nodes is over 60.

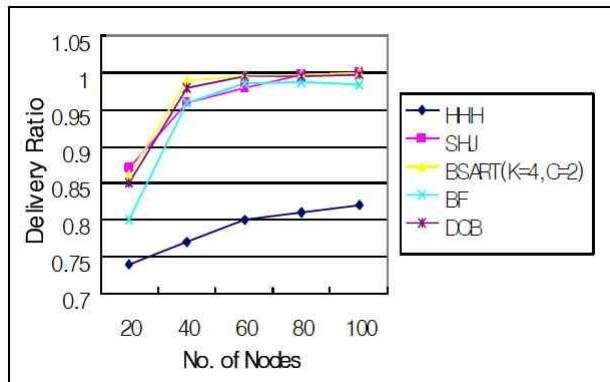


Fig. 4. message delivery ratio per nodes

Fig. 5 also shows transmission ratio when $c=2, 3, 4, 5$ to apply A-method for antenna element 1, 4, 8. In general, as c increases, A-method is used frequently and it leads message transmission with ACK. As c increases, message transmission ratio is increases consequently just as Fig. 5.

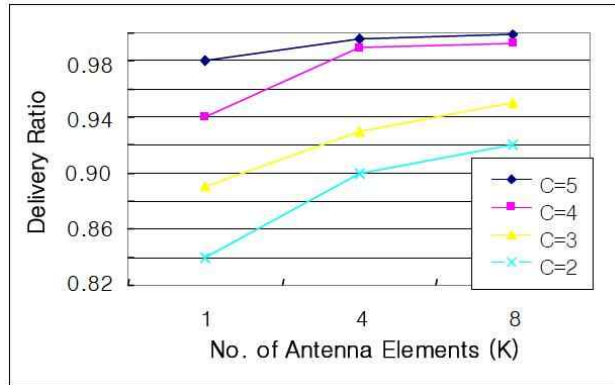


Fig. 5. message delivery ratio per antenna element

Fig. 6 shows transmission ratio as node's movement when number of nodes is 60. BF and SHJ show high ratio regardless node's movement, DCB-SD and BSART show over 90% transmission ratio. HHH shows the highest ratio as node's movement[11].

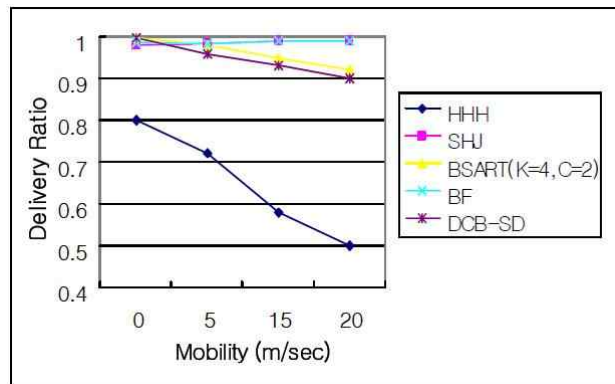


Fig. 6. message delivery ratio per mobility

Fig. 7 shows ACK processing time as c constant which decides A-method. As c is smaller and K is bigger, the processing time gets short. As K increases, the number of nodes to transmit messages per antenna element decreases and it leads c to smaller.

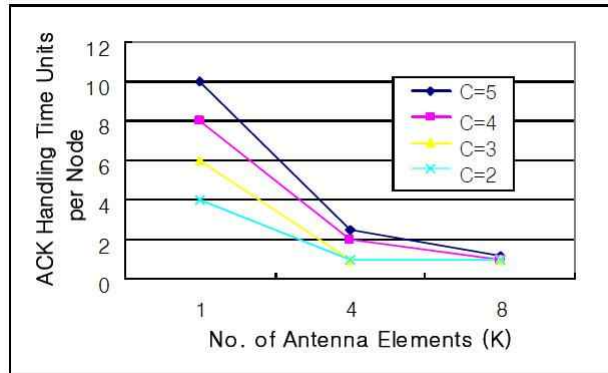


Fig. 7. ACK handling time per No. of antenna element

5. Conclusion

In this paper, we proposed BSART (Broadcasting with Selective Acknowledgements and Repeat Transmission) that provides bidirectional, low cost and reliable broadcast with switched beam antenna in the mobile ad-hoc network. We considered A-method based ACK per antenna element and R-method which only retransmission messages constant times without ACK to deal with ACK implosion that appears reliable transmission, that is, antenna elements which number of receive nodes over c , let the node retransmit message constant times, otherwise require ACK. By experiments, we proved our algorithm reduces number of broadcast message and ACK, supports reliable message transmission. The condition which under 20m/s movement speed, $K=4$ and $c=2$, we proved over 90% message transmission ratio by experiments. And close performance analysis of BSART and applicable BSART to sensor network are expected.

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